

## ERRATA LIST

### **Apollo510 SoC**

Ultra-low Power Apollo SoC Family

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# Silicon Errata for the Apollo510 SoC

## 1. Introduction

This document is a detailed compilation of known device errata for the general availability revisions, B1 and B2, of the Apollo510 SoC. Unless stated otherwise, all listed errata apply to all packages of the SoC.

## 2. Document Revision History

**Table 1: Document Revision History**

Rev No.	Date	Description
1.0	December 2024	Initial Release
2.0	February 2025	ERR024 updated - AmbiqSuite Workaround Status expanded. ERR028 updated - AmbiqSuite Workaround Status corrected. ERR033, ERR034, ERR036, ERR037 added.

### 3. Errata Summary List

Below is a list of the errata described in this document. The reference number for each erratum is listed along with its description and link to the page where detailed information can be found.

**Table 2: Errata Summary**

Erratum Number, Title and Page	Affected Silicon Revisions	Resolution Status	Workaround
"ERR001: AUDADC: MCU hangs when attempting to configure the AUDADC with disabled clock" on page 9	All existing	No fix planned	Software workaround
"ERR002: DC: Limitations with MRAM AXI bus read transactions" on page 11	All existing	Fix on future derivatives	Software workaround
"ERR003: DEBUG: In self-hosted debug, TPIU register writes when PDDBG is not power up can cause system hang" on page 12	All existing	No fix planned	Software workaround
"ERR005: DSI: Cannot complete DBI transaction when reading DSI register" on page 13	All existing	No fix planned	Software workaround
"ERR006: DSI: DSI PHY draws 8 mA when powered up" on page 14	Revision B1	Fixed on revision B2	Software workaround
"ERR007: RTC: Intermittent bus hang by reading either the CTRUP or CTRL0W registers in LP or HP mode" on page 15	All existing	No fix planned	Software workaround
"ERR008: IOM: FIFO threshold interrupt incorrectly triggered" on page 16	All existing	No fix planned	Software workaround
"ERR009: MSPI: Accessing some powered-down/unclocked memory interfaces can cause system hangs" on page 17	All existing	No fix planned	Software workaround
"ERR010: IOS: FIFO read gets stuck/stalled" on page 19	All existing	No fix planned	No workaround
"ERR011: IOS: MISO line is not tri-stated when CE is de-asserted" on page 20	All existing	No fix planned	Hardware and Software workarounds
"ERR012: IOS: FIFO mode failures with certain FIFO_BASE and FIFOPTR settings" on page 21	All existing	No fix planned	Software workaround
"ERR013: IOS: Subordinate interrupt (SLINT) is not bonded out to external pin" on page 22	All existing	No fix planned	Software workaround
"ERR014: MEMORY: Restrictions on use of DMA to TCM" on page 23	All existing	Fix on future derivatives	Software workaround
"ERR015: MEMORY: SIMO Buck cannot be enabled via INFO0 setting" on page 24	All existing	No fix planned	Software workaround
"ERR016: MSPI: Peripheral accesses not guaranteed when clock source <= 48 MHz" on page 25	All existing	No fix planned	No workaround
"ERR018: MSPI: Crossing a memory boundary during DMA transfer causes device hang" on page 26	All existing	No fix planned	Software workaround

Table 2: Errata Summary

Erratum Number, Title and Page	Affected Silicon Revisions	Resolution Status	Workaround
"ERR019: MSPI: Upper data lines are pulled low instead of staying in high impedance mode" on page 27	All existing	No fix planned	No workaround
"ERR020: MSPI: Mixed Mode 1-1-4 does not work as expected" on page 28	All existing	No fix planned	Software workaround
"ERR021: PDM: High OSR causes aliasing and PDM mic distortion to occur during the PDM-to-PCM conversion" on page 29	All existing	Fix on future derivatives	Software workaround
"ERR022: PWRCTRL: APB bus hang when accessing unpowered OTP registers or INFO space" on page 30	All existing	Fix on future derivatives	No workaround
"ERR023: PWRCTRL: CPU cannot go into deepsleep when either OTP or ROM is powered on" on page 31	All existing	Fix on future derivatives	Software workaround
"ERR024: PWRCTRL: MCU continues to use the clock for LP mode (HFRC) after switching from LP to HP mode" on page 32	All existing	No fix planned	Software workaround
"ERR025: PWRCTRL: SIMO Buck fails to transition from Active Mode to LP Mode" on page 33	All existing	No fix planned	Software workaround
"ERR026: PWRCTRL: Some power domains might not power up as expected after a SWPOI reset" on page 34	All existing	Fix on future derivatives	Software workaround
"ERR027: RSTGEN: Brown-out reset status bit may get set inadvertently during power-up" on page 35	All existing	No fix planned	Software workaround
"ERR028: RTC: CB field value is unpredictable when year = 99 and CEB = 1" on page 36	All existing	No fix planned	Software workaround
"ERR029: STIMER: Constraints on writing to SCMPRn registers and handling Compare interrupts" on page 37	All existing	No fix planned	Software workaround
"ERR030: SYSPLL: Special case where EXTREFCLK cannot be set as the SYSPLL clock" on page 39	All existing	Fix on future derivatives	Software workaround
"ERR031: USB: Induced D+ output pulse may cause unintended disconnect" on page 40	All existing	No fix planned	No workaround
"ERR032: DEBUG: SWO pin goes low during deepsleep" on page 41	All existing	Fix on future derivatives	Software workaround
"ERR033: Boot Loader: Keybank restrictions when used for OTA encryption" on page 42	All existing	Fix on future derivatives	Software workaround
"ERR034: Boot Loader: SBL's OEM recovery does not use INFO0 settings for wired update" on page 43	All existing	Fixed in SBL version 1.16	No workaround
"ERR036: Secure Boot ROM: SDIO1 can only be used in 1-bit mode for MRAM recovery" on page 44	All existing	No fix planned	Hardware and software workaround

**Table 2: Errata Summary**

<b>Erratum Number, Title and Page</b>	<b>Affected Silicon Revisions</b>	<b>Resolution Status</b>	<b>Workaround</b>
"ERR037: IOS/IOSFD: Erroneous XCMPRF interrupt triggered" on page 45	All existing	No fix planned	Software workaround

## 4. Detailed Silicon Errata

This section gives detailed information about each erratum. Information covered for each erratum includes the following:

- **Erratum Reference Number and Title** – Lists reference number and title of the erratum
- **Description** – Provides a detailed description of the erratum
- **Affected Silicon Revisions** – Specifies the silicon revisions on which the erratum exists
- **Application Impact** – Describes the impact of the erratum on a user application
- **Workarounds** – Proposes software or hardware workarounds to minimize or eliminate the risk of the erratum occurring
- **Erratum Resolution Status** – Specifies which silicon revision, if any, that the erratum was initially fixed
- **AmbiqSuite Workaround Status** – Specifies whether the erratum has been worked around in the AmbiqSuite software



## 4.1 ERR001: AUDADC: MCU hangs when attempting to configure the AUDADC with disabled clock

### 4.1.1 Description

If an AUDADC register access is attempted when the clock source connection has been removed, the MCU will hang. If the AUDADC is on and any loss-of-clock condition occurs, this can result in a CPU hang. The loss-of-clock condition could be one of the following:

- Disabling XTAL\_HS while the AUDADC is being clocked by it.
- When the AUDADC is clocked by EXTREFCLK on GPIO15 and its pad function changes from EXTREFCLK to another preventing the clock input, or the clock connection is removed physically, or the external clock source itself stops providing the clock.
- Selecting "OFF" for the AUDADC clock source.
- Disabling SYSPLL when the AUDADC is clocked by the SYSPLL.
- Disabling XTAL\_HS when the AUDADC is clocked by the PLL and XTAL\_HS is SYSPLL reference clock.
- Disabling EXTREFCLK when the AUDADC is clocked by the PLL and EXTREFCLK is SYSPLL reference clock.

Also, powering on the AUDADC and accessing an AUDADC register after a software reset, but the clock source before the reset has not been enabled after the reset, an AUDADC register access will cause an MCU hang to occur.

### 4.1.2 Affected Silicon Revisions

This silicon erratum applies to all revisions of Apollo510 SoC.

### 4.1.3 Application Impact

This issue may affect user applications that clock the AUDADC module with the high-speed crystal (XTAL\_HS), the SYSPLL or by an external clock (EXTREFCLK).

### 4.1.4 Workarounds

The workarounds for this issue are as follows:

1. To fully reset the AUDADC to its default settings, perform a full POR which sets the AUDADC clock to HFRC\_48MHz.
2. Before powering down the AUDADC, set the module's clock to an HFRC/HFRC2 selection if the clock selection was the XTAL\_HS, SYSPLL or EXTREFCLK.

Then there should be no problem when the AUDADC is next initialized and powered on. The module's clock source may then be reselected upon re-enabling the AUDADC, making sure that the intended clock is present and enabled.

1. The firmware should not set the Clock Select to OFF for AUDADC and should not disable the direct/indirect clock source(s) currently used by the AUDADC.
2. When using EXTREFCLK, be sure not to reconfigure GPIO15 to another function, or stop the external clock source when the AUDADC module is powered on, or assign an alternate function to GPIO15 altogether.

This ensures that the clock source for AUDADC is always active and the CPU hang issue doesn't occur during device operation.

#### **4.1.5 Erratum Resolution Status**

There currently are no plans to fix this erratum.

#### **4.1.6 AmbiqSuite Workaround Status**

The Ambiqsuite SDK invokes `am_hal_sysctrl_clkmuxrst_low_power_init()` in the `am_hal_pwrctrl_low_power_init()` function, which sets the clock to HFRC\_48MHz to prevent the hang when enabling the AUDADC.

**NOTE:** Clock source selection for the AUDADC is managed by the AUDADC HAL and the Clock Manager, and the user does not need to worry about the clock configuration. So enabling XTAL\_HS no longer requires the user application to do it - it is done by the AUDADC/I2S/PDM HAL by calling the Clock Manager. The Clock Manager will not turn off a clock requested by AUDADC as long as it is not released by AUDADC as well.

## **4.2 ERR002: DC: Limitations with MRAM AXI bus read transactions**

### **4.2.1 Description**

When the Display Controller (DC) is fetching data from multiple memories for its multiple layers and one of the memories is MRAM, failures occur in the form of incorrect data being read or an AXI bus hang.

### **4.2.2 Affected Silicon Revisions**

This silicon erratum applies to all revisions of Apollo510 SoC.

### **4.2.3 Application Impact**

This issue may cause AXI bus hang.

### **4.2.4 Workarounds**

A workaround for this issue is to not use MRAM as one of the memories if multiple memories are needed. However, if all of the layers only read from MRAM (one memory), it is ok. It is recommended to set the DC layers in the memories other than MRAM, such as SSRAM or external pSRAM.

### **4.2.5 Erratum Resolution Status**

There are no plans to fix this erratum on any future silicon revision of the Apollo510 devices. This erratum is intended to be fixed in future derivatives of the Apollo5 family.

### **4.2.6 AmbiqSuite Workaround Status**

The AmbiqSuite SDK doesn't provide a workaround for this issue.

### **4.3 ERR003: DEBUG: In self-hosted debug, TPIU register writes when PDDBG is not power up can cause system hang**

#### **4.3.1 Description**

On the M55, self-hosted debug components should be powered on automatically when the M55 writes to any of the debug subsystem registers (ITM, WDT, TPIU, etc.). In the Apollo510, writing to the TPIU registers does not automatically power-on the debug subsystem. Therefore software must manually enable the debug power domain, PDDBG, by setting the PWRCTRL\_DEVPWREN\_PWRENDDBG bit, and then can access the debug registers safely. This is required before accessing any self-hosted debug functions, including enabling the SWO for logging or messages. If software writes to a TPIU register when the PDDBG is off, the system hangs. Note that manually enabling PDDBG is not required when an external debugger is attached.

#### **4.3.2 Affected Silicon Revisions**

This silicon erratum applies to all revisions of Apollo510 SoC.

#### **4.3.3 Application Impact**

This issue may cause a CPU hang if the PDDBG power domain is not powered up before writing to debug registers.

#### **4.3.4 Workarounds**

A workaround for this issue is to explicitly enable the PDDBG power domain before writing the TPIU registers. If the PDDBG is off, then the self-hosted wakeup may fail. Self-hosted debug means that it is only the CPU accessing the ITM/TPIU, and this workaround is still required. If the TPIU is programmed just for SWO, then the software workaround is to enable the PDDBG when in use and then manually power down the PDDBG.

#### **4.3.5 Erratum Resolution Status**

There are no plans at this time to fix this erratum.

#### **4.3.6 AmbiqSuite Workaround Status**

The AmbiqSuite SDK's HAL routines, such as `am_hal_tpiu_enable()` and `am_hal_itm_enable()`, and their complementary functions `am_hal_itm_disable()` and `am_hal_tpiu_disable()`, explicitly handle the power-up and power-down of the debug domain.

## 4.4 ERR005: DSI: Cannot complete DBI transaction when reading DSI register

### 4.4.1 Description

Cannot complete the DBI transaction when reading a DSI display register and the display is not connected. When executing a DSI read command, the correct sequence is:

1. DBI sends read command.
2. DSI IP translates this command to DSI and sends this command to the display.
3. When DSI gets returned data from display, it sets DBI\_DataValid and returns data to DBI.
4. DBI receives data and enters idle state.

But when the display is not connected or is damaged, the DSI cannot get returned data and an ACK from the display. It will enter a busy state, and will not set DBI\_DataValid. As a result the DBI cannot be freed and will stay in the busy state. The DC status register will indicate "DBI/SPI CS is busy" (bit 14 at 0x400A00FC).

Disabling/enabling DBIB (bit 4 in MODE register) to force DBIB to idle state (bit 26 in DBIB\_CFG register) and force CSX to high/low level (bit 29 and bit 30 in DBIB\_CFG register) fails to clear bit 14 in NEMADC\_REG\_STATUS. So the DBIB bus cannot be freed after a read failure.

If MIPICFG\_EN\_DVALID signal is used, then the DBI\_DV (DBI\_DataValid) signal must also be used to terminate the read transaction.

### 4.4.2 Affected Silicon Revisions

This silicon erratum applies to all revisions of Apollo510 SoC.

### 4.4.3 Application Impact

This issue may cause the DBI to remain in a busy state when a display panel becomes unconnected or is otherwise unresponsive in a user applications.

### 4.4.4 Workarounds

When disabling EN\_DVALID after read operations in all APIs for DSI reads, the DBI/DSI can be released from busy mode.

### 4.4.5 Erratum Resolution Status

There currently are no plans to fix this erratum.

### 4.4.6 AmbiqSuite Workaround Status

EN\_DVALID has been disabled after read operation in all APIs for DSI reads. There is a timeout in the SDK when checking to see if the panel is connected and responding so that DBI/DSI can be released from busy mode.

## **4.5 ERR006: DSI: DSI PHY draws 8 mA when powered up**

### **4.5.1 Description**

When the DSI PHY is powered up, a VSS power switch produces an additional 8 mA of current leakage. The VSS power switch should be opened when DSI PHY is powered up but there is a PN diode in the PMOS switch that creates a forward bias current from VDDF to VSS.

### **4.5.2 Affected Silicon Revisions**

This silicon erratum applies to all “B” revisions of Apollo510 SoC up to revision B1. It is fixed on revision B2.

### **4.5.3 Application Impact**

This issue causes an additional 8 mA current draw when the DSI PHY is powered on and being used due to leakage.

### **4.5.4 Workarounds**

There currently is no workaround for this issue.

### **4.5.5 Erratum Resolution Status**

This erratum is fixed in silicon revision B2.

### **4.5.6 AmbiqSuite Workaround Status**

The AmbiqSuite SDK cannot provide a workaround to prevent the extra current draw.

## **4.6 ERR007: RTC: Intermittent bus hang by reading either the CTRUP or CTRL-LOW registers in LP or HP mode**

### **4.6.1 Description**

An intermittent bus hang may result from reading either the RTC's CTRUP or CTRL-LOW register in Low Power (LP) or High Performance (HP) mode. When the read access occurs close to the rising edge of the 100 Hz RTC clock, the read finite state machine (FSM) could potentially transition to an unknown state and get stuck there causing a bus hang. Only a reset returns the FSM back to normal.

### **4.6.2 Affected Silicon Revisions**

This silicon erratum applies to all revisions of Apollo510 SoC.

### **4.6.3 Application Impact**

Under certain timing conditions, this issue may cause a bus hang recoverable only by reset.

### **4.6.4 Workarounds**

A workaround for this issue is to avoid reading the two RTC registers close to the rising edge of the RTC clock. The workaround can either leverage the system timer (STIMER) provided by the application to minimize the power impact, or use the reserved timer in the HAL to capture the rising edge. Setting the read delay to around 10  $\mu$ s is adequate. If the CTRUP/CTRL-LOW register reads are NOT within the RTC's ISR which would occur coincident with the clock's rising edge, then an additional delay waiting for the next rising edge would need to be incurred.

### **4.6.5 Erratum Resolution Status**

There are no plans at this time to fix this erratum.

### **4.6.6 AmbiqSuite Workaround Status**

The AmbiqSuite SDK has the workaround mentioned above implemented.

## **4.7 ERR008: IOM: FIFO threshold interrupt incorrectly triggered**

### **4.7.1 Description**

In normal read operation, the FIFO threshold interrupt (THR) and associated register bit (INTSTAT\_THR) are asserted when the number of valid bytes in the read FIFO (FIFOPTR\_FIFOnSIZ) equals or exceeds the value set in the read threshold field (FIFOTHR\_FIFORTHR), and similarly for write operation.

When doing a FIFO read transaction (DMA or non-DMA), the write threshold check is not gated off. This could trigger an incorrect/invalid write interrupt which should be ignored. If the application uses the wrong interrupt to check the read data, incorrect data processing could result.

### **4.7.2 Affected Silicon Revisions**

This silicon erratum applies to all revisions of Apollo510 SoC.

### **4.7.3 Application Impact**

The effect of this issue on user applications depends on how the application handles IOM interrupts and whether FIFO pointers are evaluated properly before initiating a FIFO read operation to determine how much data is ready to be read. If an invalid write interrupt is received and handled as a read command completed and read data is ready to use, then processing wrong data could result.

### **4.7.4 Workarounds**

The workaround for this issue is for the application to do the following:

1. To prevent the triggering of a wrong interrupt, the FIFOWTHR should be set to zero when performing a read command and the FIFORTHR should be set to zero when performing a write command.
2. Always inspect the actual FIFO pointers before determining how much data is available to read. If the application inspects the actual FIFO pointer properly, then errant (false threshold) interrupts can be ignored and there should not be any adverse issues due to this erratum.

### **4.7.5 Erratum Resolution Status**

There currently are no plans to fix this erratum.

### **4.7.6 AmbiqSuite Workaround Status**

The AmbiqSuite SDK provides all necessary memory and register access functions to enable the application to implement the stated workaround.



## 4.8 ERR009: MSPI: Accessing some powered-down/unlocked memory interfaces can cause system hangs

### 4.8.1 Description

An explicit memory access (read, write and instruction fetch) or a data and instruction pre-fetch to a memory that is in a powered down or unlocked state may cause a system hang. If there is dirty data in the data cache, a cacheable access to another data region may cause a cache-line eviction when attempting to write back the cache line to memory. If that memory is powered down, then a system hang may occur.

The following table lists access types and resulting error codes/conditions for accesses to either SSRAM, MSPI or MSPI's PSRAM memory.

Access Type by CPU	SSRAM	MSPI/PSRAM
Memory Access in Retention/Standby	SSRAM is out of retention if CPU is active. Auto-Wakeup occurs for accesses from other mains.	MSPI is on. Software can put PSRAM in Standby / low power mode. MSPI does not know the PSRAM is in a low-power state, so it will continue to process read/write requests which may get no response and may cause a system hang.
Memory Access if powered down	RAXI returns SLVERR for all mains.	System hang occurs. <sup>1</sup>
Memory access if powered up but not clocked	There is no SSRAM clock disable.	System hang occurs.
Register Access in Retention	Registers in MCUCTRL and PWRCTRL are always on.	MSPI is still on even if the PSRAM is put into a low power mode. MSPI register accesses will work correctly.
Register Access if power off	Registers are in MCUCTRL and PWRCTRL and are always on.	Decoder will detect and return a SLVERR.
Register Access if power on but not clocked	Registers in MCUCTRL and PWRCTRL are always on.	Decoder will not block the access, so system hang occurs.
Protection violation	Protection violation will be raised, no access will be generated on the system fabric.	Protection violation will be raised, no access will be generated on the system fabric.

1. When the M55 attempts to access a powered down MSPI device, the MSPI device cannot respond to the request. The system does not detect this condition, so an error is not returned. This results in unsatisfied memory transactions that can hang the system. This issue is unique to MSPI, but applies to all 4 MSPI instances. Accesses to other powered down memories (SSRAM, DTCM, etc) will return the expected memory fault.

### 4.8.2 Affected Silicon Revisions

This silicon erratum applies to all revisions of the Apollo510 SoC.

### 4.8.3 Application Impact

This issue may cause a system hang that would be recoverable only by a Power On Reset (POR) or Watchdog reset.

#### **4.8.4 Workarounds**

To avoid accessing memories that are in a powered down, unlocked or error state, as per the above table, software may use a Memory Protection Unit (MPU) region to block explicit memory accesses, and then use a Data Synchronization Barrier (DSB) instruction and an Instruction Synchronization Barrier (ISB) instruction to ensure that all in-flight transactions have been completed. Any subsequent access to this region will trigger an MPU exception that can be handled in software. Protection violations stay in the CPU and generate exceptions. So, exceptions are raised as long as the MPU is configured to block all accesses.

If the memory to be powered down includes cacheable read/write data, this might result in cache-line evictions and the MPU region strategy described above is not able to block these accesses. Possible workarounds for this case are as follows:

- Do not power down MSPI/PSRAM devices if that memory is used for writeable data and thus might have dirty cache lines in the cached data.
- Clean the data cache before powering down MSPI, then implement a memory barrier, then use the MPU to block accesses. Note that there is a significant cost in cleaning the cache in terms of time and power.
- Make the PSRAM region write-through, then use the DSB/ISB and MPU strategy above to block further accesses. Note that this option has power and performance implications.

#### **4.8.5 Erratum Resolution Status**

There are no plans at this time to fix this erratum on the Apollo510 SoC.

#### **4.8.6 AmbiqSuite Workaround Status**

The AmbiqSuite SDK does not implement a workaround to prevent the described conditions that may cause a hang.

## **4.9 ERR010: IOS: FIFO read gets stuck/stalled**

### **4.9.1 Description**

If the SPI main pauses the SPI SCK, the Apollo510 may get stuck waiting for the next SCK from the SPI main when accessing IOS registers. The control state machine of the IOS assumes that once the interface starts an operation (read or write), it finishes it and the bus is held off until that happens because only one operation can take place with the LRAM at a time. The read or write request is asserted for one interface clock cycle, so if the clock stops the request will be held and the IOS (and MCU) will be stalled.

This could also happen when inside an ISR, causing extended delays in interrupt context. For example, the AmbiqSuite SDK HAL implements larger size IOS nonblocking transactions using a SW assisted replenishing of the hardware FIFO by servicing the FSIZE interrupts. This issue could cause the ISR handler to get stuck when servicing the interrupt.

### **4.9.2 Affected Silicon Revisions**

This silicon erratum applies to all revisions of Apollo510 SoC.

### **4.9.3 Application Impact**

Getting stuck in an ISR may block other interrupts from being serviced. For example, such an occurrence may be the STIMER tick interrupt being blocked resulting in delayed scheduling of the RTOS. After the occurrence of several such blocking events, the STIMER may get overrun (e.g., the compare value is less than the counter without INSTAT getting set).

### **4.9.4 Workarounds**

There is no workaround for this issue. The main needs to ensure that it does not insert long pauses in the clock once it has started a transaction.

### **4.9.5 Erratum Resolution Status**

There are no plans to implement any further fix for this erratum in the Apollo510 family of SoCs.

### **4.9.6 AmbiqSuite Workaround Status**

There is no software workaround in the AmbiqSuite SDK.

## **4.10 ERR011: IOS: MISO line is not tri-stated when CE is de-asserted**

### **4.10.1 Description**

When configured as a SPI subordinate using the IOS module, the Apollo510 does not tri-state the MISO pin when CE is de-asserted. Instead, the MISO pin is driven static low when CE is driven high. This condition exists for the half-duplex as well as the full-duplex IOS instances.

### **4.10.2 Affected Silicon Revisions**

This silicon erratum applies to all revisions of Apollo510 SoC.

### **4.10.3 Application Impact**

If there are multiple subordinates on the same SPI bus as an Apollo510 configured as a SPI subordinate, other subordinate devices will be prevented from driving data onto the MISO line. In effect this prevents the sharing of the SPI bus with other subordinate devices.

### **4.10.4 Workarounds**

Workarounds include:

1. Do not have any other subordinate devices on the SPI bus.
2. Add an external tri-state buffer between the Apollo510 MISO pin and the MISO line of the SPI bus so that the MISO pin on Apollo510 does not drive the bus when CE is de-asserted by the SPI main device.
3. Implement a software workaround that reconfigures and tri-states the Apollo510 MISO pin when the Apollo510 CE signal is de-asserted (driven high) by the SPI main device.

### **4.10.5 Erratum Resolution Status**

There currently are no plans to fix this erratum.

### **4.10.6 AmbiqSuite Workaround Status**

There is no specific workaround in the AmbiqSuite SDK for this issue.

## **4.11 ERR012: IOS: FIFO mode failures with certain FIFO\_BASE and FIFOPTR settings**

### **4.11.1 Description**

There are two conditions which may cause FIFO mode to fail because of a conflict with the host-side register space:

- FIFO\_BASE is set to 0x10 (halfway into the LRAM) when FIFO reads are to be executed.
- FIFOPTR is set within the range 0x78 to 0x7F.

The address pointer is set to the value of the host access and then mapped to the LRAM (i.e., FIFO space) by adding 8. Thus host accesses to the host-side register space will cause a wraparound of the LRAM address which is not correct.

### **4.11.2 Affected Silicon Revisions**

This silicon erratum applies to all revisions of Apollo510 SoC.

### **4.11.3 Application Impact**

The impact of this issue on user applications is that FIFO read transfers will be corrupted because the LRAM address will not be incremented correctly. If FIFO\_BASE is set to 0x10, the actual FIFO base address is 0x80.

### **4.11.4 Workarounds**

The workaround for this issue is to ensure that FIFO\_BASE is not set to 0x10, and that the initial FIFOPTR is never set to an address within the host-side register space.

### **4.11.5 Erratum Resolution Status**

There currently are no plans to fix this erratum.

### **4.11.6 AmbiqSuite Workaround Status**

The AmbiqSuite SDK does not perform any error checking to ensure that FIFO\_BASE and FIFOPTR are configured properly.

## **4.12 ERR013: IOS: Subordinate interrupt (SLINT) is not bonded out to external pin**

### **4.12.1 Description**

The half-duplex IOS0 Subordinate module's interrupt (SLINT) is a function select for GPIO162. However, this GPIO pad is not bonded out to an external pin on the Apollo510 BGA. Therefore, the IOS0's supported and built-in interrupt mechanism is not operational.

### **4.12.2 Affected Silicon Revisions**

This silicon erratum applies to all revisions of Apollo510 SoC.

### **4.12.3 Application Impact**

The effect of this issue is that it requires either another GPIO to be used as the IOS0 interrupt pin, or the full-duplex IOS1/IOS2 combination to be used in place of the half-duplex IOS0.

### **4.12.4 Workarounds**

Since the IOS Subordinate interrupt for the full-duplex IOS (SLFDINT) is operational, a workaround for this issue is to use that IOSFD module, either in half-duplex or the IOS1/IOS2 pair in full duplex mode. Another workaround for this issue on the Apollo510 SoC is to use another GPIO interrupt to mimic the SLINT behavior.

### **4.12.5 Erratum Resolution Status**

There are no plans to fix this erratum on any existing or planned Apollo510 package.

### **4.12.6 AmbiqSuite Workaround Status**

The second workaround stated above is implemented in the AmbiqSuite SDK. In the half-duplex IOS examples, `ios_fifo` and `ios_burst`, the `SLINT_GPIO` is set to 1 to use another GPIO interrupt to mimic the SLINT behavior for the IOS0 in the Apollo510.

## 4.13 ERR014: MEMORY: Restrictions on use of DMA to TCM

### 4.13.1 Description

There are three known restrictions on DMAing to TCM.

1. A DMA transfer cannot cross a 4 kB boundary.
2. Access to TCM when it is powered down returns an incorrect error condition (Success).
3. Access to TCM while the CPU is in deepsleep with memory retained returns an error.<sup>(1)</sup>

### 4.13.2 Affected Silicon Revisions

This silicon erratum applies to all revisions of Apollo510 SoC.

### 4.13.3 Application Impact

This issue may cause multiple issues including data loss/corruption or bus hang when DMAing to TCM.

### 4.13.4 Workarounds

A workaround for the 4 kB boundary issue is to ensure that DMA transfers are constructed in software so as not to cross a 4 kB boundary in TCM.

There are no workarounds for the other two issues; the application must ensure that TCM is not powered down when an access is attempted and that access to TCM must not occur when the CPU is in deepsleep.

### 4.13.5 Erratum Resolution Status

There are no plans to fix this erratum on any future silicon revision of the Apollo510. This erratum is intended to be fixed in future derivatives of the Apollo5 family.

### 4.13.6 AmbiqSuite Workaround Status

There is no workaround in the AmbiqSuite SDK for this issue. The user should avoid this issue in the application.

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1. This is correct behavior of the Arm<sup>®</sup> M55 architecture. It is mentioned here to notify the user of this TCM usage restriction.

## **4.14 ERR015: MEMORY: SIMO Buck cannot be enabled via INFO0 setting**

### **4.14.1 Description**

The SIMO buck cannot be enabled automatically via INFO0.

### **4.14.2 Affected Silicon Revisions**

This silicon erratum applies to all revisions of Apollo510 SoC.

### **4.14.3 Application Impact**

This issue has little effects on user applications. The only impact is that the SIMO Buck needs to be initiated in software during system initialization.

### **4.14.4 Workarounds**

Enabling SIMO buck can be done in software.

### **4.14.5 Erratum Resolution Status**

There currently are no plans to fix this erratum.

### **4.14.6 AmbiqSuite Workaround Status**

The AmbiqSuite SDK workaround for this issue is to enable the SIMO buck via a HAL function: `am_hal_pwrctrl_control(AM_HAL_PWRCTRL_CONTROL_SIMOBUCK_INIT, 0)`.



## **4.15 ERR016: MSPI: Peripheral accesses not guaranteed when clock source <= 48 MHz**

### **4.15.1 Description**

When an MSPI clock source lower than or equal to 48 MHz is selected, not all MSPI peripheral accesses can be guaranteed. Thus, for MSPI0 and MSPI3, only HFRC\_96MHz, HRFC2\_125MHz, HFRC\_192MHz or HRFC2\_250MHz may be selected in the CLKGEN\_MSPIIOCLKCTRL\_MSPInIOCLKSEL register fields. For MSPI1 and MSPI2, only HFRC\_96MHz or HFRC\_192MHz may be selected.

### **4.15.2 Affected Silicon Revisions**

This silicon erratum applies to all revisions of the Apollo510 SoC.

### **4.15.3 Application Impact**

With clock options lower than 96 MHz disabled, the lower limit of the MSPI's SCLK at a supported divider of 32 (set in the MSP\_DEV0CFG\_CLKDIV0) is increased.

### **4.15.4 Workarounds**

There is no workaround available for this erratum.

### **4.15.5 Erratum Resolution Status**

There currently are no plans to fix this erratum.

### **4.15.6 AmbiqSuite Workaround Status**

The AmbiqSuite SDK has limited the MSPI clock source selection to be higher than 48 MHz in the HAL.

## **4.16 ERR018: MSPI: Crossing a memory boundary during DMA transfer causes device hang**

### **4.16.1 Description**

A DMA transfer which has a start address near the upper boundary of a memory block and the transfer extends into the next memory block, a device hang occurs. The root cause is that a DMA burst is fixed to 0, so the DMA address will not change when it crosses the memory boundary.

This condition applies for several boundaries, which are the DTCM - SRAM0, SRAM0 - SRAM1 and SRAM1 - SRAM2 boundaries. The address ranges for the affected memory spaces are the following for the Apollo510:

- DTCM: 0x20000000 - 0x2007FFFF
- SSRAM0: 0x20080000 - 0x2017FFFF
- SSRAM1: 0x20180000 - 0x2027FFFF
- SSRAM2: 0x20280000 - 0x2037FFFF

In addition, this susceptibility to device hang occurs when a DMA transfer crosses a 4 kB boundary in DTCM.

### **4.16.2 Affected Silicon Revisions**

This silicon erratum applies to all existing revisions of Apollo510 SoC.

### **4.16.3 Application Impact**

This issue causes a device hang and requires a reset to recover.

### **4.16.4 Workarounds**

A workaround for this issue is to ensure that a DMA transfer does not attempt to cross the DTCM - SSRAM memory address boundary.

### **4.16.5 Erratum Resolution Status**

There currently are no plans to fix this erratum.

### **4.16.6 AmbiqSuite Workaround Status**

It is up to the user to ensure that a memory boundary crossing in DMA transfers does not occur.

## **4.17 ERR019: MSPI: Upper data lines are pulled low instead of staying in high impedance mode**

### **4.17.1 Description**

Behavior of the upper data lines (IO2 and IO3) during the instruction phase of mixed-mode (1-1-4 or 1-4-4) transfers is preventing IO3 to function properly as the nHOLD signal, as is done on certain NAND devices. When nHOLD is pulled low at the start of the transaction and despite pull-ups present, it causes the chip to ignore all other signals. The SoC should leave the upper data lines floating during the instruction phase of mixed-mode transfers.

### **4.17.2 Affected Silicon Revisions**

This silicon erratum applies to all revisions of Apollo510 SoC.

### **4.17.3 Application Impact**

Certain NAND devices requiring IO3 to be kept high during mixed-mode (1-1-4 or 1-4-4) operation may not function properly.

### **4.17.4 Workarounds**

Currently there is no workaround for this issue. Use of certain NAND devices requiring IO3 to be kept high during mixed-mode (1-1-4 or 1-4-4) operation is not recommended or supported.

### **4.17.5 Erratum Resolution Status**

There currently are no plans to fix this erratum.

### **4.17.6 AmbiqSuite Workaround Status**

The AmbiqSuite SDK does not provide a solution for and does not support the use of these devices.

## **4.18 ERR020: MSPI: Mixed Mode 1-1-4 does not work as expected**

### **4.18.1 Description**

A glitch occurs on the D0 line between address and data in mixed mode D4, or 1-1-4. The glitch is observed only during write operation in 1-1-4 mode and its occurrence may cause data write failures. Read operation is not affected and therefore it does not pose a problem for XIP/XIPMM reads.

### **4.18.2 Affected Silicon Revisions**

This silicon erratum applies to all revisions of Apollo510 SoC.

### **4.18.3 Application Impact**

This issue may cause write data errors in MSPI D4 mode when the glitch is sampled by an external device.

### **4.18.4 Workarounds**

A workaround for this issue is to emulate D4 mode in software. Disable the ADDR phase (DEV0XIP\_XIPSENA = 0), then add extra data at the beginning of the data phase to emulate D4 mode. There should be no problem for XIP/XIPMM reads but there is no workaround for XIPMM write issue in 1-1-4 mode.

Note that XIP/XIPMM across 1-1-4 interface is not a common use case since it is normally used in NAND flash which does not support XIP/XIPMM.

### **4.18.5 Erratum Resolution Status**

There currently are no plans to fix this erratum.

### **4.18.6 AmbiqSuite Workaround Status**

The workaround code is released in all three NAND flash drivers of the AmbiqSuite SDK.

## **4.19 ERR021: PDM: High OSR causes aliasing and PDM mic distortion to occur during the PDM-to-PCM conversion**

### **4.19.1 Description**

In sampling configurations/frequencies with high Oversampling Ratio ( $> 128$ ), the audio from the digital mic has distortion during speech. Most of the distortion comes from aliasing which is occurring during the PDM-to-PCM conversion. With a DMIC clock of 3.072 MHz and an OSR of 192, there is distortion from 1.6 kHz to 16 kHz. When OSR=192, the MIC input signal bandwidth is greater than  $F_s/2$  ( $= 16/2 = 8$  kHz). If the mic input signal spectrum is wider than 8 kHz, a significant amount of aliasing occurs. Therefore, a maximum OSR of 128 is supported.

### **4.19.2 Affected Silicon Revisions**

This silicon erratum applies to all revisions of Apollo510.

### **4.19.3 Application Impact**

This issue may cause poor audio quality in certain sampling configurations.

### **4.19.4 Workarounds**

A workaround for this issue is to not use a sampling configuration with an OSR of  $> 128$ . The use of either of the following configurations is recommended:

- $F_{pdm\_cko} = 3.072$  MHz,  $F_s = 24$  kHz, OSR=128
- $F_{pdm\_cko} = 1.536$  MHz,  $F_s = 16$  kHz, OSR=96

### **4.19.5 Erratum Resolution Status**

There are no plans to fix this erratum on any future silicon revision of the Apollo510. This erratum is intended to be fixed in future derivatives of the Apollo5 family.

### **4.19.6 AmbiqSuite Workaround Status**

There is no workaround implemented in the AmbiqSuite SDK. It is up to the user to configure the PDM with a sampling setting which does not result in unacceptable aliasing.

## **4.20 ERR022: PWRCTRL: APB bus hang when accessing unpowered OTP registers or INFO space**

### **4.20.1 Description**

An access to the OTP info space or OTP registers when the OTP is powered down will result in an APB bus hang. The OTP power domain is powered up by setting the PWRCTRL\_DEVPWREN\_PWRENOTP field to Enable. This field is enabled by default.

### **4.20.2 Affected Silicon Revisions**

This silicon erratum applies to all revisions of Apollo5 and Apollo5B SoCs.

### **4.20.3 Application Impact**

This issue may cause an APB bus hang which would require a power-on reset to recover.

### **4.20.4 Workarounds**

There is no workaround for this issue. The application must ensure OTP is powered on before attempting to access OTP registers or OTP infospace. Please note that while OTP is powered on at reset, for low power operation it should be turned off whenever not in use.

### **4.20.5 Erratum Resolution Status**

There are no plans to fix this erratum on any future silicon revision of the Apollo510. This erratum is intended to be fixed in future derivatives of the Apollo5 family.

### **4.20.6 AmbiqSuite Workaround Status**

There is no workaround implemented in the AmbiqSuite SDK for this issue. The OTP is powered on at reset and should be turned off whenever not in use, especially for low power operation. The application must power on the OTP before attempting to access OTP registers or OTP infospace.

## **4.21 ERR023: PWRCTRL: CPU cannot go into deepsleep when either OTP or ROM is powered on**

### **4.21.1 Description**

The SoC design requires that the CPU be powered on when either OTP or ROM is powered on.

### **4.21.2 Affected Silicon Revisions**

This silicon erratum applies to all revisions of Apollo5 and Apollo5B SoCs.

### **4.21.3 Application Impact**

Without proper handling in software, the OTP and ROM power domains will see large leakage current when the CPU is powered down. Please note that for low power operation, the recommendation is to turn off OTP and ROM whenever not in use, even if CPU is active.

### **4.21.4 Workarounds**

The workaround for this issue is to make sure that OTP and ROM are off when CPU is inactive (in deepsleep).

### **4.21.5 Erratum Resolution Status**

There are no plans to fix this erratum on any future silicon revision of the Apollo510. This erratum is intended to be fixed in future derivatives of the Apollo5 family.

### **4.21.6 AmbiqSuite Workaround Status**

The AmbiqSuite SDK prevents the CPU from going into deepsleep if either OTP or ROM is still powered on.

## **4.22 ERR024: PWRCTRL: MCU continues to use the clock for LP mode (HFRC) after switching from LP to HP mode**

### **4.22.1 Description**

After transitioning from low power (LP) mode to high performance (HP) mode, the MCU still uses the clock for LP (HFRC) after the switch if the clock for HP (HFRC2) is not enabled before switching. For the HP HFRC2 clock to immediately go into effect upon transition from LP mode to HP mode, the HFRC2 clock must be enabled and allowed a settling time for the HFRC2 clock to stabilize before the transition.

### **4.22.2 Affected Silicon Revisions**

This silicon erratum applies to all revisions of Apollo510 SoC.

### **4.22.3 Application Impact**

The MCU still being clocked by the LP mode clock, HFRC, after transitioning from LP mode to HP mode may be unexpected, and the slower than expected clock rate may need to be accounted for.

### **4.22.4 Workarounds**

A workaround for this issue is to enable HFRC2 and allow a wait time of up to 15  $\mu$ s for the HFRC2 clock to stabilize before switching to HP mode.

### **4.22.5 Erratum Resolution Status**

There currently are no plans to fix this erratum.

### **4.22.6 AmbiqSuite Workaround Status**

The AmbiqSuite SDK has integrated the software workaround described above into the PWRCTRL HAL. When waking up from deepsleep to HP mode, the CPU wakes up even if not operating in HP mode yet. During the transition period, the CPU runs in LP mode (clocked by HFRC). The `AM_HAL_STALL_CPU_HPWAKE` in the PWRCTRL HAL should be set to 1 if it is necessary to block the CPU after waking up until running in HP mode (clocked by HFRC2). Note that the default setting of 0 for `AM_HAL_STALL_CPU_HPWAKE` is better for reducing wakeup latency.



## **4.23 ERR025: PWRCTRL: SIMO Buck fails to transition from Active Mode to LP Mode**

### **4.23.1 Description**

An automatic SIMO Buck transition mode, which is enabled by setting both PWRCTRL\_TONCNTRCTRL register fields LPMODESWOVR and ENABLELPOVR to 0x1, causes the SIMO Buck to transition to active mode if there is an increase in load current, but otherwise stays in Low Power (LP) Mode. Once the SIMO Buck transitions into Active Mode in deepsleep mode, it periodically retries to go into LP Mode. The SIMO Buck can transition from LP to Active if the temperature change and load change are gradual. However, it cannot handle the transition if there is a rapid change in temperature or load current. Because of this limitation, production trims do not make use of SIMO Buck automatic mode transitioning, and it is recommended that these PWRCTRL bits remain cleared.

### **4.23.2 Affected Silicon Revisions**

This silicon erratum applies to all revisions of Apollo510 SoC.

### **4.23.3 Application Impact**

In automatic SIMO Buck transition mode, if the simobuck transitions into Active Mode in deepsleep mode and fails to transition back into Low Power (LP) Mode, there could be a high deepsleep current (over 2 mA).

### **4.23.4 Workarounds**

The workaround is to not use the SIMO Buck automatic transition mode. Instead, before entering deepsleep mode monitor the temperature and force the SIMO Buck into active mode if the temperature is higher than 50 degrees C and put/leave the SIMO Buck in LP mode if lower than 50 degrees C. After entering deepsleep, or even if in active mode, perform a periodic check of the temperature to see if the SIMO Buck needs to or can transition its power mode.

### **4.23.5 Erratum Resolution Status**

There are no plans at this time to fix this erratum since the current production power trims do not require SIMO Buck automatic mode transitioning.

### **4.23.6 AmbiqSuite Workaround Status**

The AmbiqSuite SDK's Spot Manager HAL helps the application manage SOC power states across temperature.

## **4.24 ERR026: PWRCTRL: Some power domains might not power up as expected after a SWPOI reset**

### **4.24.1 Description**

All the power domains can be trimmed to be powered on after a SWPOI reset. In the failure case, some of the power domains might not power up as expected after a SWPOI reset. This is a hardware startup issue which could result in non-functional peripherals/memories.

### **4.24.2 Affected Silicon Revisions**

This silicon erratum applies to all revisions of Apollo510.

### **4.24.3 Application Impact**

This issue may cause some power domains to not be powered up as expected, making it not functional and resulting in some or all memories having content different than that before the SWPOI reset.

### **4.24.4 Workarounds**

A workaround for this issue is to check the power enable/status fields to ensure that each one's power enable bit matches its power status bit. This is done by performing register reads, comparing values and taking needed action after any reset for differences in any of the following register fields in the PWRCTRL set of registers:

1. SSRAMPWREN with SSRAMPWRST
2. DEVPWREN with DEVPWRSTATUS
3. MEMPWREN with MEMPWRSTATUS (except PWRSTCACHE)
4. AUDSSPWREN with AUDSSPWRSTATUS

If there is a mismatch of any power enable field and corresponding power status field (e.g., PWREN=1 and PWRST=0), perform the following steps:

1. Power off the specific domain (set PWREN=0).
2. Wait for 2.5  $\mu$ s.
3. Power on (set PWREN=1).
4. Wait for PWRST to become set (should not take more than 50  $\mu$ s).

### **4.24.5 Erratum Resolution Status**

There are no plans to fix this erratum on any future silicon revision of the Apollo510. This erratum is intended to be fixed in future derivatives of the Apollo5 family.

### **4.24.6 AmbiqSuite Workaround Status**

The workaround for this issue is implemented in the pre-installed SBL and hence is not visible to or a part of a user application.

## **4.25 ERR027: RSTGEN: Brown-out reset status bit may get set inadvertently during power-up**

### **4.25.1 Description**

The brown-out reset status bit, RSTGEN\_STAT\_BORSTAT, may inadvertently get set due to the brown-out signals powering up inconsistently during system power-up. Whether the status bit gets set is influenced by the voltage levels of the power supplies (VDDH/VDDP/VDDA) and the ramp rate of these supplies.

### **4.25.2 Affected Silicon Revisions**

This silicon erratum applies to all revisions of Apollo510 SoC.

### **4.25.3 Application Impact**

This issue may cause the brown-out reset status bit to get set incorrectly during system power-up.

### **4.25.4 Workarounds**

The recommendation is to clear this status bit (RSTGEN\_STAT\_BORSTAT) after initial power-up. The RSTGEN\_STAT register is a mirror of the actual hardware status register (RSTSTAT), which has already been cleared by bootrom after any reset event including initial power up. The bootrom and/or the secure bootloader maintain and update the RSTGEN\_STAT register with appropriate status settings after each reset event. While this register is intended to be read-only, all bits in the register, including reserved bits, are in fact writable. Therefore, application software should take great care when writing this register.

### **4.25.5 Erratum Resolution Status**

There currently are no plans to fix this erratum.

### **4.25.6 AmbiqSuite Workaround Status**

An SDK HAL workaround is implemented in the function `am_hal_pwrctrl_low_power_init()`. If that function is not called by the application, the recommendation is to implement one of the following workarounds:

1. Execute the following code: `if ( RSTGEN->STAT_b.POASTAT ) { RSTGEN->STAT_b.BORSTAT = 0; }`
2. On a production line, after initial power up, a debugger writes the field to 0.
3. Any reset event after power up will clear the BORSTAT status bit and resolve the issue.

## 4.26 ERR028: RTC: CB field value is unpredictable when year = 99 and CEB = 1

### 4.26.1 Description

When the RTC\_CTRUP\_CEB bit is set to enable the Century bit (CB) to change, the CB toggles whenever and as long as the Year field (CTRYR) is 99. This happens not just on rollover from 99 to 00 but toggles randomly, which is (essentially) every RTC clock.

### 4.26.2 Affected Silicon Revisions

This silicon erratum applies to all revisions of Apollo510 SoC.

### 4.26.3 Application Impact

This issue may affect any application using POSIX time which uses January 1, 1970 as its epoch. In such systems a common test involves checking the correct value of the Century bit upon rollover from 1999 to 2000.

### 4.26.4 Workarounds

The workaround for this issue is to keep the CEB cleared, disabling the CB bit from automatically toggling when the CTRYR register field rolls over from 99 to 00. The century value should be maintained in the CB field by software.

### 4.26.5 Erratum Resolution Status

There currently are no plans to fix this erratum.

### 4.26.6 AmbiqSuite Workaround Status

The AmbiqSuite SDK has been modified as follows:

- CEB is no longer supported. The bit should be kept cleared (default) when setting up the RTC in the HAL.
- No automatic toggle of the CB field when the CTRYR field rolls over from 99 to 00.

Note that the Century Bit, RTC\_CTRUP\_CB, which is used to specify the century (for leap year calculation purposes), was not previously documented correctly in the Apollo510 register set and has been corrected. This bit should be set to 1 if the century is 20xx, and it should be set to 0 if the century is 21xx.

## **4.27 ERR029: STIMER: Constraints on writing to SCMPRn registers and handling Compare interrupts**

### **4.27.1 Description**

Compare interrupts are delayed by one STIMER clock. Additionally, it takes two STIMER clock cycles for the write to an SCMPRn register (where n is 0 to 7 representing one of the STIMER Compare registers) to get operated on. These timing issues put constraints on the minimum value of delta that can be applied to SCMPRn, which is 4 STIMER clock cycles.

In addition, back-to-back writes to SCMPRn may not work reliably (i.e., take the last value) unless the application ensures not to write within two STIMER clock cycles of the previous one. As well, after writing to SCMPRn, the application needs to wait for at least three STIMER clock cycles before reading it back for the new value to be reflected.

It takes two STIMER clock cycles for the write to STCFG to take effect. This caused 2 extra cycles to add to the minimum delta.

### **4.27.2 Affected Silicon Revisions**

This silicon erratum applies to all revisions of Apollo510 SoC.

### **4.27.3 Application Impact**

This issue may affect user applications by not generating an STIMER interrupt when it is expected, or with unreliable read/write of SCMPRn. Also, when updating the Compare interrupt time by writing to SCMPRn, it is possible that the application may still get a stale interrupt corresponding to the old value even after a new value is written to SCMPRn because of the latency with a write operation. This could happen if SCMPRn is written too close to the imminent interrupt.

### **4.27.4 Workarounds**

The workaround for this potential issue is to ensure that the minimum delta for the next compare is specified correctly. Internal latencies must be accounted for by adjusting (reducing) the delta that is actually supplied in the SCMPRn register, keeping in mind that the programmed delta must be at least 1 STIMER clock cycles. For Apollo510 SoCs, this latency correction is 3 cycles. Therefore, the minimum valid delta setting is 4 STIMER clock cycles.

Also the application needs to handle back-to-back writes to SCMPRn and ensure not to write within two STIMER clock cycles of the previous one, and then wait for at least three STIMER clock cycles before reading it back for the new value to be reflected. Application also needs to handle the unlikely event of a stale Compare interrupt.

### **4.27.5 Erratum Resolution Status**

There currently are no plans to fix this erratum.

#### **4.27.6 AmbiqSuite Workaround Status**

The AmbiqSuite HAL contains the workaround for these delays by internally adjusting the delta amount to be written to SCMPRn. Specifically, the HAL will account for the Compare interrupts being delayed by one STIMER clock by adjusting the delta value.

In addition, the HAL accounts for an extra 2 STIMER clock cycles of latency for the writes to SCMPRn by adjusting the delta value. The HAL will also handle the proper back-to-back writes to COMPARE and read-back, inserting waits if needed.

There is no workaround in the HAL for rare stale Compare interrupts, which could occur if SCMPRn is written too close to the imminent interrupt. The application needs to check for and handle such a case.

## **4.28 ERR030: SYSPLL: Special case where EXTREFCLK cannot be set as the SYSPLL clock**

### **4.28.1 Description**

The SYSPLL can be clocked by either the high-speed crystal oscillator (XTALHS) or an external reference clock (EXTREFCLK) through a glitch-less mux within the SYSPLL. If XTALHS had been enabled at any time after reset and then disabled, then the selection of the EXTREFCLK as the SYSPLL clock source cannot be made. If the XTALHS had been enabled and then disabled, it must be re-enabled to be able to transition the SYSPLL clock source from XTALHS (default setting) to the EXTREFCLK.

If XTALHS had not been enabled prior to selecting the clock source for the SYSPLL or is not present in the system, then EXTREFCLK can be selected as the SYSPLL clock source directly (by setting the MCUCTRL\_PLLCTL0\_FREFSEL bit to EXTREFCLK).

### **4.28.2 Affected Silicon Revisions**

This silicon erratum applies to all revisions of Apollo510 SoC.

### **4.28.3 Application Impact**

This issue may prevent the SYSPLL from selecting the desired clock source or either clock source.

### **4.28.4 Workarounds**

A software workaround for this issue is to have both clocks available and enabled when configuring the SYSPLL to use the EXTREFCLK if the XTALHS had been enabled and disabled prior to SYSPLL clock selection. The EXTAL\_HS can be disabled after SYSPLL clock selection if it is not needed elsewhere.

Note that if XTALHS had not been enabled prior to selecting the clock source for the SYSPLL or is not present in the system, then EXTREFCLK can be selected as the SYSPLL clock source directly (by setting the MCUCTRL\_PLLCTL0\_FREFSEL bit to EXTREFCLK).

### **4.28.5 Erratum Resolution Status**

There are no plans to fix this erratum on any future silicon revision of the Apollo510. This erratum is intended to be fixed in future derivatives of the Apollo5 family.

### **4.28.6 AmbiqSuite Workaround Status**

The AmbiqSuite SDK implements the software workaround for this issue and has implemented the Clock Manager HAL, which includes managing the input clock for the SYSPLL.

## **4.29 ERR031: USB: Induced D+ output pulse may cause unintended disconnect**

### **4.29.1 Description**

An output pulse on the D+ line while VDDUSB0P9 and/or VDDUSB33 are/is rising may be interpreted by a host as a connect event immediately followed by a disconnect one, causing the host USB SW to report about the unexpected disconnect from Apollo510. Such a report/message could be safely ignored for the USB-compliant hosts which would attempt USB device re-enumeration. An enumeration attempt performed when all USB power rails are stable succeeds.

### **4.29.2 Affected Silicon Revisions**

This silicon erratum applies to all revisions of Apollo510 SoC.

### **4.29.3 Application Impact**

The Apollo510 may fail to connect or stay connected with USB hosts that deviate from strict USB 2.0 specifications.

### **4.29.4 Workarounds**

USB 2.0 compliant hosts are not affected by this erratum. While there is no workaround for the hosts that are not strictly USB 2.0 compliant, the proper system initialization and shutdown sequences minimize the chances of the non-compliant host being affected by the erratum. The proper USB power-up/power-down sequences can be found in the USB section of the Apollo510 SoC Datasheet.

### **4.29.5 Erratum Resolution Status**

There currently are no plans to fix this erratum.

### **4.29.6 AmbiqSuite Workaround Status**

No workaround is needed in the AmbiqSuite SDK.



## 4.30 ERR032: DEBUG: SWO pin goes low during deepsleep

### 4.30.1 Description

The enabled SWO pin goes low during deepsleep mode which violates the SWO specifications. This signal is expected to stay high during deepsleep. The SWO output is in the PDDBG power domain which does remain powered when the M55 core goes to sleep. However, these signals are routed through the MCUH power domain which is powered down in deepsleep resulting in the SWO signal being isolated low.

### 4.30.2 Affected Silicon Revisions

This silicon erratum applies to all revisions of Apollo510 SoC.

### 4.30.3 Application Impact

This issue causes loss of the use of the SWO output when the device enters deepsleep mode.

### 4.30.4 Workarounds

A workaround for this issue is to ensure the SWO print pipeline is flushed and that the SWO pin is set high and configured as a GPIO before going into deepsleep. When exiting deepsleep, the GPIO should be reconfigured for the SWO function.

### 4.30.5 Erratum Resolution Status

There are no plans to fix this erratum on any future silicon revision of the Apollo510 SoC. This erratum is intended to be fixed in future derivatives of the Apollo5 family.

### 4.30.6 AmbiqSuite Workaround Status

The AmbiqSuite SDK provides a function, `am_bsp_debug_printf_deepsleep_prepare()`, as a reference for users to work around this issue. The user must ensure all printing has completed before calling this function, and it should be called just before and just after going to deepsleep. Please note that implementing this workaround impacts deepsleep power, as the system will only reach the `CORE_DEEPSLEEP` level rather than the `SYS_DEEPSLEEP` level. Also see the `PWRCTRL_SYSPWRSTATUS` register.

## **4.31 ERR033: Boot Loader: Keybank restrictions when used for OTA encryption**

### **4.31.1 Description**

Keybank1, Keybank2 and Keybank3 keys cannot be used as AES keys for use with secure OTAs or wired updates. Keybank0 keys (4 total at kek index 0x80-0x83) can be used.

### **4.31.2 Affected Silicon Revisions**

This silicon erratum applies to all revisions of Apollo510 SoC.

### **4.31.3 Application Impact**

If keys in a keybank other than Keybank0 are used for AES encryption, this issue causes encryption errors when used in conjunction with SBL based OTAs.

There is no impact on usage of hardware keys KCP and KCE (key index 0 and 1). They can continue to be used. Also, usage of the keybanks outside of Ambiq SBL is not restricted.

### **4.31.4 Workarounds**

Use only Keybank0 keys (kek index 0x80-0x83). They can be used as AES keys for secure OTAs or wired updates through Ambiq SBL.

### **4.31.5 Erratum Resolution Status**

There are no plans to fix this erratum on any future silicon revision of the Apollo510 SoC. This erratum is intended to be fixed in future derivatives of the Apollo5 family.

### **4.31.6 AmbiqSuite Workaround Status**

No workaround is needed in the AmbiqSuite SDK.

## **4.32 ERR034: Boot Loader: SBL's OEM recovery does not use INFO0 settings for wired update**

### **4.32.1 Description**

The Secure Boot Loader (SBL) does not use the settings for wired recovery from INFO0, but instead uses the default settings in INFO1 even when INFO0 is valid and the settings are configured. The flag used by the SBL to determine which settings to use, INFO0 or INFO1, is not initialized by the time the OEM recovery is initiated, so the SBL always picks up the INFO1 settings.

### **4.32.2 Affected Silicon Revisions**

This silicon erratum applies to all revisions of the Apollo510 SoC.

### **4.32.3 Application Impact**

This issue causes the SoC to always use factory settings in INFO1 for the SBL regardless of the setting of the INFO0/INFO1 selection flag. This issue comes into play only when doing an application and GPIO-initiated recovery. It works as intended, i.e., INFO0 settings will be used, for OEM recovery in case the OEM certifications fail.

### **4.32.4 Workarounds**

There is no workaround for this issue.

### **4.32.5 Erratum Resolution Status**

This issue is fixed in SBL version 1.16 or later and can be applied to all Apollo510 devices.

### **4.32.6 AmbiqSuite Workaround Status**

This issue is fixed in the SBL for versions 1.16 or later, and is in AmbiqSuite SDK releases 5.0.0 and later. SDK5.0.0 includes an SBL OTA update image that can be used to update earlier devices.

### **4.33 ERR036: Secure Boot ROM: SDIO1 can only be used in 1-bit mode for MRAM recovery**

#### **4.33.1 Description**

SDIO1 can only be used in 1-bit mode for MRAM recovery. SDIO0 is fully functional. The boot ROM recovers the SBL (~64 KB), and the SBL recovers the OEM's image (up to 256 KB).

#### **4.33.2 Affected Silicon Revisions**

This silicon erratum applies to all revisions of the Apollo510 SoC.

#### **4.33.3 Application Impact**

This issue requires that SDIO0 be used for MRAM recovery when 4-bit or 8-bit mode is desired.

#### **4.33.4 Workarounds**

A workaround for this issue is to use SDIO0 which allows the SBL to work in 1, 4 or 8-bit mode.

#### **4.33.5 Erratum Resolution Status**

There currently are no plans to fix this erratum on any future silicon revision of the Apollo510 SoC.

#### **4.33.6 AmbiqSuite Workaround Status**

The AmbiqSuite SDK does not affect, and is not affected by, this issue.

## **4.34 ERR037: IOS/IOSFD: Erroneous XCMPRF interrupt triggered**

### **4.34.1 Description**

When using the IOS or IOSFD, the XCMPRF (Read from FIFO space transfer complete) flag is incorrectly set, instead of the XCMPRR (Read from register transfer complete) flag, on host reads of the 0x7C FIFOCNTLO (FIFO Counter Low-Byte) Host Address Register. This same behavior is seen during host reads of 0x7D FIFOCNTUP (FIFO Counter High-Byte) Host Address Register) as well.

A read by the host of 0x7C (or 0x7D) triggers the XCMPRF interrupt rather than the XCMPRR interrupt. A host read of FIFO data at 0x7F also triggers the XCMPRF interrupt as would be expected. Therefore, depending on the host reads, extra interrupts during read operations could occur.

### **4.34.2 Affected Silicon Revisions**

This silicon erratum applies to all revisions of the Apollo510 SoC.

### **4.34.3 Application Impact**

This issue will cause extraneous and misleading interrupts if XCMPRF interrupts are enabled.

### **4.34.4 Workarounds**

Possible workarounds for this issue are the following:

1. Do not use 0x7C/7D commands to get the FIFO counter. Instead use the direct access area to store the data size and exchange it during the handshake.
2. Add a FIFO space check in the interrupt routine to check for the amount of space used in the FIFO to filter the extra interrupt and make sure the read operation is complete.

### **4.34.5 Erratum Resolution Status**

There currently are no plans to fix this erratum.

### **4.34.6 AmbiqSuite Workaround Status**

The AmbiqSuite SDK examples use the first workaround to handle this issue.

## 5. Ordering Information

**Table 3: Ordering Information for Apollo510 SoC**

Device Name	Orderable Part Number	Packing
Apollo510 SoC	AP510NFA-xxx	Tape and Reel



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